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### **Intermittent Behavior and Synchronization of Two Coupled**

(c) and (d) are the corresponding time series for the cases (a) and (b), respectively. Order parameter for two values of  $c_2$  at the neighborhood of the transition to a synchronized state.

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### **PDF Super Twisting Sliding Mode in Motion Control Systems**

$b_4(w, z) + k_3 b_3(w, z)$ . The sliding function parameters  $k_1$ ,  $k_2$  and  $k_3$  should stabilize the sliding mode dynamic (21). For a proper choice of such constant parameters one can linearize

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### **Resonant forced motions of a weakly coupled linear and**

This paper is concerned with the investigation of the resonant periodic motions, and their stability, for a weakly coupled linear and strictly non-linear oscillator, subject to weak periodic forcing.

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### **Topological Methods in Nonlinear Analysis Vol 9 no 1 1997**

Topological Methods in Nonlinear Analysis Journal of the Julius Schauder Center Volume 9, 1997, 77-106 ON THE FUNDAMENTAL SOLUTION OF A PERTURBED HARMONIC OSCILLATOR LEV KAPITANSKI - IGOR RODNIANSKI - KENJI YAJIMA To Olga Alexandrovna Ladyzhenskaya, with respect and admiration o. Introduction In the Schrodinger picture, the change in time of the wave function of a quantum system is governed

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### **ac power signal German translation Linguee**

dass dieses niederfrequente Informationssignal der hochfrequenten Trägerschwingung erst über eine nichtlineare Funktion der Kanäle durch Demodulation gewonnen werden muss. [fgf.de](http://www.fgf.de) For operation the analogue input requires a 24 V auxiliary voltage that is made available either directly from the 24 V AC power supply or indirectly via the 24 V AC terminals of the basic unit.

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b) Care este noua valoare a decrementului logaritmic dacă se ataează masei inițiale o masă  $m_1 = m$ . Răspuns:  $kg_6450, m = , mN_4636, k = , 1940, = . 2.E4$  Un sistem masă-arc-amortizor viscos este deplasat o distanță  $mm_200 = a$  apoi lăsat liber.

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### **DE102007039408A1 Kransteuerung Kran und Verfahren**

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